

# Qichen Fu

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## EDUCATION

### Carnegie Mellon University, School of Computer Science

Master of Science in Robotics; GPA: 4.24/4.33

Pittsburgh, PA  
Aug. 2020 - Aug. 2022

### University of Michigan - Ann Arbor, College of Engineering

Bachelor of Science in Computer Science (dual degree with SJTU); GPA: 4.00/4.00

Ann Arbor, MI  
Aug. 2018 - Apr. 2020

### Shanghai Jiao Tong University

Bachelor of Engineering in Electrical and Computer Engineering (dual degree with UM); GPA: 3.73/4.00

Shanghai, China  
Sept. 2016 - Aug. 2020

## WORK EXPERIENCE

### Apple

Machine Learning Engineer in AI/ML - Machine Intelligence Neural Design (MIND)

Seattle, WA  
Aug. 2022 - Present

#### Apple Intelligence – LLM Optimization

- Developed *LazyLLM*, a novel method that allows language models to dynamically select different subsets of tokens from the context in different generation steps, to significantly accelerate the generation without fine-tuning. For instance, in the multi-document QA task, *LazyLLM* accelerates the prefilling stage of the Llama 2 7B by 2.34x while maintaining accuracy. This work is accepted at Efficient Systems for Foundation Models workshop at ICML 2024.
- Developed Superposition Prompting, a novel RAG prompting method that allows the LLM to process input documents in parallel prompt paths, facilitates a 93× reduction in compute time while improving accuracy by 43% on the NaturalQuestions-Open dataset with the MPT-7B. This work is accepted at ICML 2024.
- Developed Speculative Streaming, a new speculative decoding paradigm that does not require a draft model, achieves 1.8× - 3.1× speedups in diverse tasks. This work is under review at EMNLP 2024.

#### Head Gestures for AirPods

- Led the development of machine learning models and algorithms for head gesture detection, allowing AirPods users to privately respond to Siri with a simple head nod yes or shake no. This feature is shipped at WWDC 2024.

#### Apple Vision Pro

- Built a multi-host multi-GPU distributed training infrastructure in PyTorch, supporting efficient large-scale training.
- Developed a temporal action classification model that predicts user activities from videos, which is used to mitigate the False Positives of Pinch Detection when the user is holding an object.

#### Leadership

- Mentored a Research Intern to develop FastSR-NeRF, an efficient NeRF+SR pipeline that speeds up NeRF training by 23× and inference by 18× while maintaining high quality. This work is accepted as an *Oral* paper at WACV 2024.

## SELECTED PUBLICATIONS

### LazyLLM: Dynamic Token Pruning for Efficient Long Context LLM Inference

Qichen Fu, Minsik Cho, Thomas Merth, Sachin Mehta, Mohammad Rastegari, Mahyar Najibi

ES-FoMo @ ICML 2024

### Superposition Prompting: Improving and Accelerating Retrieval-Augmented Generation

Thomas Merth, Qichen Fu, Mohammad Rastegari, Mahyar Najibi

ICML 2024

### Speculative Streaming: Fast LLM Inference without Auxiliary Models

Nikhil Bhendawade, Irina Belousova, Qichen Fu, Henry Mason, Mohammad Rastegari, Mahyar Najibi

Arxiv 2024

### eDKM: An Efficient and Accurate Train-time Weight Clustering for Large Language Models

Minsik Cho, Keivan A Vahid, Qichen Fu, ..., Peter Zatloukal

IEEE CAL 2024

### Deformer: Dynamic Fusion Transformer for Robust Hand Pose Estimation

Qichen Fu, Xingyu Liu, Ran Xu, Juan Carlos Niebles, Kris M. Kitani

ICCV 2023

### Domain Adaptive Hand Keypoint and Pixel Localization in the Wild

Takehiko Ohkawa, Yu-Jhe Li, Qichen Fu, Ryosuke Furuta, Kris M. Kitani, Yoichi Sato

ECCV 2022

### Sequential Voting with Relational Box Fields for Active Object Detection

Qichen Fu, Xingyu Liu, Kris M. Kitani

CVPR 2022

### Ego4D: Around the World in 3,000 Hours of Egocentric Video

Kristen Grauman, ..., Qichen Fu, ..., Jitendra Malik

CVPR 2022 Oral, Best Paper Finalist

## RESEARCH EXPERIENCE

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### **KLab, Carnegie Mellon University**

Research Assistant; Advisor: Prof. Kris Kitani

Pittsburgh, PA

Oct. 2020 - Aug. 2022

- Led the video de-identification, state change object detection benchmark and challenge development of the EGO4D dataset.
- Developed a Dynamic Fusion Transformer framework for robust 3D hand pose estimation from videos.
- Developed a pixel-wise voting function with a Relational Box Field to robustly detect active objects under occlusions.

### **Fouhey AI Lab, University of Michigan**

Research Assistant; Advisor: Prof. David Fouhey

Ann Arbor, MI

May 2019 - May 2020

- Developed an unsupervised object detection system predicting bounding boxes and articulation type for objects in video.
- Built an artificial object detection system for image filtering, reaching an accuracy of 95.06% and an AUC score of 0.92.

### **Fessler Research Group, University of Michigan**

Research Assistant; Advisor: Prof. Jeffrey A. Fessler, Prof. Yuni Dewaraja

Ann Arbor, MI

Oct. 2018 - May 2020

- Developed complex-valued U-Net for MRI reconstruction, reducing parameters by 50% compared to the vanilla U-Net.
- Developed a novel method integrating back-projection and 3D U-Net for PET reconstruction directly from measurements.

## TEACHING EXPERIENCE

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### **Carnegie Mellon University**

Pittsburgh, PA

- 16-824: Visual Learning and Recognition (Spring 2022), advised by Prof. Deepak Pathak
- 16-720B: Computer Vision (Fall 2021), advised by Prof. Kris Kitani

### **University of Michigan**

Ann Arbor, MI

- EECS 442: Computer Vision (Winter 2020), advised by Prof. David Fouhey
- EECS 442: Computer Vision (Fall 2019), advised by Prof. David Fouhey

## HONORS

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**University of Michigan:** Jackson and Muriel Lum Scholarship, James B. Angell Scholar, University Honors

**Shanghai Jiao Tong University:** National Scholarship, Undergraduate Excellent Scholarship, MiYuan Public Welfare Scholarship